Geometry without algebra is dumb! - Algebra without geometry is blind!
   - David Hestenes

The principal argument for the adoption of geometric algebra is that it provides a single, simple mathematical framework which eliminates the plethora of diverse mathematical descriptions and techniques it would otherwise be necessary to learn.
   - Allan McRobie and Joan Lasenby
To David Hestenes,
founder, chief theoretician, and most forceful advocate
for modern geometric algebra and calculus,
and inspiration for this book.

To my Grandchildren,
Aida, Pablo, Miles, Graham.
Contents

Contents iii

Preface vii

To the Student xi

I Linear Algebra 1

1 Vectors 3
   1.1 Oriented Lengths ........................................ 3
   1.2 \(\mathbb{R}^n\) ........................................ 12

2 Vector Spaces 15
   2.1 Vector Spaces ........................................ 15
   2.2 Subspaces ........................................ 20
   2.3 Linear Combinations .................................. 22
   2.4 Linear Independence .................................. 24
   2.5 Bases ........................................ 27
   2.6 Dimension ........................................ 30

3 Matrices 33
   3.1 Matrices ........................................ 33
   3.2 Systems of Linear Equations ......................... 45

4 Inner Product Spaces 51
   4.1 Oriented Lengths ...................................... 51
   4.2 \(\mathbb{R}^n\) ...................................... 56
   4.3 Inner Product Spaces ................................ 57
   4.4 Orthogonality ...................................... 63
Preface

Linear algebra is part of the standard undergraduate mathematics curriculum because it is of central importance in pure and applied mathematics. It was not always so. The wide acceptance of vector methods did not occur until early in the twentieth century. The pioneers were two physicists: the American Josiah Willard Gibbs and the Englishman Oliver Heaviside, beginning in the late 1870’s. Linear algebra allows easy algebraic manipulation of vectors. But it is not the latest word on the algebraic manipulation of geometric objects.

Geometric algebra is an extension of linear algebra pioneered by the American physicist David Hestenes in the 1960’s. Geometric algebra and its extension to geometric calculus unify, simplify, and generalize vast areas of mathematics, including linear algebra, vector calculus, exterior algebra and calculus, tensor algebra and calculus, quaternions, real analysis, complex analysis, and euclidean, noneuclidean, and projective geometries. They provide a common mathematical language for many areas of physics (classical and quantum mechanics, electrodynamics, special and general relativity), computer science (graphics, robotics, computer vision), engineering, and other fields.¹

Just as linear algebra algebraically manipulates one dimensional objects (vectors) in a coordinate-free manner, geometric algebra algebraically manipulates higher dimensional objects (multivectors) in a coordinate-free manner. Even within linear algebra, many topics are improved by using geometric algebra.

The material in this book subsumes, unifies, and generalizes the vector, complex, quaternion (spinor), exterior (Grassmann), and tensor algebras.

I believe that the time has come to incorporate some geometric algebra in the introductory linear algebra course. This book provides a text for such a course. Single variable calculus is not a prerequisite. But for most students a mathematical maturity equivalent to that gained in such a course probably is.


My A Survey of Geometric Algebra and Geometric Calculus provides an introduction for someone who already knows linear algebra. It contains a guide to further reading, online and off. It is available at the book’s webpage.
Part I of this book is standard linear algebra. Part II introduces geometric algebra. Part III covers linear transformations and their geometric algebra extensions, called outermorphisms.

A majority of the topics in the traditional linear algebra course is treated. The major exception is algorithms. For example, the algorithm for inverting a matrix is not covered. The concept and applications of the inverse are important. They are used in many places in this book. But the algorithm to compute the inverse teaches little about the concept or its applications. Similar remarks apply to algorithms for row reduction, solving systems of linear equations, evaluating determinants, computing eigenvalues and eigenvectors, etc.

To me, the benefit/cost ratio of including the algorithms is too low. I do not need them for the theoretical development. No one applies them by hand anymore – except for exercises in linear algebra textbooks! They take up a substantial fraction of the standard syllabus, time that can be better spent on other topics. Why teach them in an elementary linear algebra course?

Some exercises and problems in the text require the use of the free multiplatform Python module \texttt{GA}\textsubscript{Algebra}. It is based on the Python \texttt{symbolic} computer algebra library \texttt{SymPy (Symbolic Python)}. The file \texttt{GAAlgebraPrimer.pdf} at the book’s web site describes the installation and use of the module.

The book covers matrix arithmetic, the application of matrices to systems of linear equations, the matrix representation of linear transformations, the matrix version of the singular value decomposition, and several matrix applications. However, matrices play a smaller role than in most texts. A major reason is that matrices are used in the omitted algorithms. Also, geometric algebra often replaces matrices with better alternatives. For example, the geometric algebra definition of a determinant is intuitive and simple and does not involve matrices. And geometric algebra provides better representations than matrices for important classes of linear transformations, as shown in the text for projections, rotations, reflections, and orthogonal and skew transformations.

There are over 200 exercises interspersed with the text. They are designed to test understanding of and/or give simple practice with a concept just introduced. My intent is that students attempt them while reading the text. Then they immediately confront the concept and get feedback on their understanding. There are over 300 more challenging problems at the end of most sections. The exercises replace the “worked examples” common in most mathematical texts, which serve as “templates” for problems assigned to students. We teachers know that students often do not read the text. Instead, they solve assigned problems by looking for the closest template in the text, often without much understanding. My intent is that success with the exercises requires engaging the text.

Everyone has their own teaching style, so I would ordinarily not make suggestions about this. However, I believe that the unusual structure of this text (exercises instead of worked examples), requires an unusual approach to teaching from it. I have placed some thoughts about this in the file “LAGA Instructor.pdf” at the book’s web site. Take it for what it is worth.
There is plenty of material here for a one semester course. The actual text is only about 190 pages, rather short for a linear algebra text, much less for one incorporating geometric algebra. One reason is that I have tried to avoid the “bloated textbook syndrome”. Another is that the exercises mean that a reader will spend more time per page than is usual in an elementary mathematics text.

An instructor should be wary of adopting a nonstandard text such as this for a course as fundamental as linear algebra. It might allay worries about this to know that this book can be used as a linear algebra text, without geometric algebra. Chapters 1-4 and Sections 8.1, 8.2, 9.1-9.4, and 9.7 use no geometric algebra. They cover the majority of topics in the traditional linear algebra course, with the exception of the aforementioned algorithms and determinants. Thus an instructor can include geometric algebra as time permits, or teach a two track course, with some students studying geometric algebra and some not.

The first part of the index is a symbol index.

Please send corrections, typos, or any other comments about the book to me. I will post them on the book’s web site as appropriate.

Geometric calculus is a powerful extension of vector calculus, just as geometric algebra is a powerful extension of vector algebra. The divergence and Stokes’ theorems are special cases of a very general theorem relating derivatives to integrals. Also, complex variable theory extends to arbitrary (even and odd) dimensions. I have published a sequel to this book, Vector and Geometric Calculus. That book’s website is http://faculty.luther.edu/~macdonal/vagc/.

Acknowledgements. I thank Ian-Charles Coleman, Gabriel Demuth, Peeter Joot, Gez Keenan, Adem Semiz, Dr. Vijay Sonnad, Quirino M. Sugon Jr., and Ginanjar Utama for helpful comments. I thank Martin Barrett, Professor Philip Kuntz, James Murphy, Robert Rowley, and Professor John Synowiec for reading all/most of the text and providing extensive and helpful comments and advice. I am especially grateful to Professor Leo Dorst for providing helpful expert commentary and to Allan Cortzen, who has improved this book in many ways, including providing better proofs of several theorems. I also thank Alan Bromborsky, author of GA Algebra, for making changes which make it more useful to readers of this book. Finally, thanks to Professor Kate Martinson for help with the cover design.

---

2 Except for the definition of determinants (p. 157). Note however that determinants are not a prerequisite for anything important in the linear algebra part of the book. In particular, they are not used in the discussion of eigenvalues.
Printings

From time to time I issue new printings of this book, with corrections and minor improvements. The printing version is shown on the title page. I list below those with significant changes or with new helpful readers.

Second Printing. I thank George Craig, who asked several penetrating questions which have improved the exposition.

Fourth Printing. I have removed the old Appendix B, Software, which documented Alan Bromborsky’s Python module $\text{G}A\text{lgebra}$. The documentation there became out of date as the module improved.

A new Chapter 10 is devoted to the increasingly important conformal model of geometric algebra. It can be skipped to after reading Part II, Geometric Algebra, as the chapter does not reference Part III, Linear Transformations. I have written a Jupyter notebook cm3.ipynb based on $\text{G}A\text{lgebra}$ for making calculations in the 3D conformal model.

The current versions of GAlgebraPrimer.pdf and cm3.ipynb are available at the book’s website and are bundled with the $\text{G}A\text{lgebra}$ distribution.

I give a special thanks to Gregory Grunberg, who has done much to improve this book, especially the new Chapter 10. The book is better for his efforts.

November 2019 Printing. Theorem 6.1-G6, G7 of have been replaced with a new G6, which better captures the notion of $k$-vector. The definition of a blade has been changed to an equivalent one and moved to Section 6.1. As a result, Sections 6.1-6.5 have been rearranged.

April 2020 Printing. There are several improvements in the presentation.

October 2020 Printing. All errors known to me have been corrected. There are several improvements in the presentation.

In general the position as regards all such new calculi is this - That one cannot accomplish by them anything that could not be accomplished without them. However, the advantage is that, provided such a calculus corresponds to the innost nature of frequent needs, anyone who masters it thoroughly is able - without the unconscious inspiration of genius which no one can command - to solve the respective problems, indeed to solve them mechanically in complicated cases in which, without such aid, even genius becomes powerless. Such is the case with the invention of general algebra, with the differential calculus, ... . Such conceptions unite, as it were, into an organic whole countless problems which otherwise would remain isolated and require for their separate solution more or less application of inventive genius. - C. F. Gauss
To the Student

Linear algebra is indispensable in many disciplines, including mathematics, statistics, physics, computer science, chemistry, biology, engineering, and economics. Linear algebra is more widely used than any other college level mathematics, with the possible exception of calculus. You can see yourself that it is widely used: whenever a new concept is introduced in the text, Google it. You will find tons of links.

Most of the mathematics taught in single variable calculus courses has been known for 250 years. But mathematics is not a fixed body of knowledge, unchanged for hundreds of years. You are used to the fact that technology advances year by year. Mathematics also advances, though not as rapidly.

Linear algebra as we know it today is the result of a vast undertaking of abstraction, over centuries, unifying common aspects of many problems in many areas of mathematics and its applications. Do not translate “abstract” as “of no practical value”: abstraction gives linear algebra much of its practical power. I hope that you will appreciate this by the time you finish the book.

The central theoretical importance of linear algebra started to be recognized early in the twentieth century. A sophomore linear algebra course has been part of the standard mathematics curriculum only since the early 1970’s. The recent availability of cheap powerful computers has made it possible to solve more practical applications of linear algebra, causing an explosion of its use.

Geometric algebra as practiced today originated in the 1960’s. It is currently under vigorous development. It has found important applications in computer science (in graphics, robotics, and computer vision), engineering, and physics. It is available to game developers for the Xbox and PlayStation video game consoles. This text is an attempt to keep up with these modern developments.

Most students find linear algebra hard, even many who have done well in previous mathematics courses. There are several reasons for this:

- Linear algebra has little connection to earlier courses. For example, this text makes only occasional, nonessential, reference to calculus.
- The large number of definitions and theorems can be overwhelming.
- Reasoning dominates calculation in linear algebra. The reasoning requires what has been called “a mathematical frame of mind”. This is a new way of thinking, difficult to describe to those who have not acquired it.
How should you cope with these difficulties? Research clearly shows that actively engaging course material improves learning and retention. Here are some ways to actively engage the material in this book:

- **Read** Study the text. This may not be your habit, but many parts of this book require reading and rereading and rereading again later before you understand.

- Instructors in your previous mathematics courses have probably urged you to try to understand, rather than simply memorize. That advice is especially appropriate for this text.

- Many statements in the text require some thinking on your part to understand. Take the time to do this instead of simply moving on. Sometimes this involves a small computation, so have paper and pencil on hand.

- Definitions are important. Take the time to understand them. You cannot know a foreign language if you do not know the meaning of its words. So too with mathematics. You cannot know an area of mathematics if you do not know the meaning of its defined concepts.

- Theorems are important. Take the time to understand them. If you do not understand what a theorem says, then you cannot understand its applications.

- Exercises are important. Attempt them as you encounter them in the text. They are designed to test your understanding of what you have just read. Some are trivial, there just to make sure that you are paying attention. Do not expect to solve them all. Even if you cannot solve an exercise you have learned something: you have something to learn!

The exercises require you to think about what you have just read, think more, perhaps, than you are used to when reading a mathematics text. This is part of my attempt to help you start to acquire that “mathematical frame of mind”.

Write your solutions neatly in clear correct English.

- Proofs are important, but perhaps less so than the above. On a first reading, don’t get bogged down in a difficult proof. On the other hand, one goal of this course is for you to learn to read and construct mathematical proofs better. So go back to those difficult proofs later and try to understand them.

- Take the above points seriously!

Appendix A, *Prerequisites*, describes the mathematical background necessary to read this text. You might want to look it over now, to make sure that you are ready.

Some exercises and problems in the text require calculations unfeasible to perform by hand. GalgebraPrimer.pdf, available at the book’s webpage, describes how to install and use the computer algebra system Galgebra for this. It is written in Python, a free multiplatform language.
Index

*  
  adjoint, 144
  dual, 109
  transpose, 41

A†, 98
C[a, b], 26, 60
C* [a, b], 137
E, 192
P, 17
Pn, 17
[i]≤, 44
&, 202
G3, 81
Gn, 93
G±, 97
I, 84
L3, 7
R3, 9
RN, 12, 56
RN, 189
U⊥, 66
f*, 144
∩, 201
o, 206
×, 112
∪, 201
ej, 99
e±, 190
ej, 52
∞, 190
i, 84
⇔, 202
⇒, 202
∈, 201
· (inner product)
  Gn, 101
  Rn, 56

inner product space, 57
oriented lengths, 51

|, 101
MB, 128
PB, 122
PU(v), 67
Pu(v), 52
Rθ, 89, 126
i, 151
→, 205
~, 113
L(U, V), 143
⟨A⟩j, 96
⟨M⟩k, 96
N(A), 47
N(f), 140
⊕, 66
∧ (outer product)
  G3, 76
  Gn, 101
Rn, 193
⊥, 64, 66
R(f), 140
eiθ, 85
⊆, 201
→, 205
fj, 148, 150
v‖, v⊥, 66
∥ || (norm)
  Gn, 99
  Rn, 14
complex number, 86
inner product space, 58
oriented area, 73
oriented length, 3
oriented solid, 79
vector space, 61
\[ f_{\mathcal{F}}, \quad 164 \]
\[ f_{\mathcal{O}}, \quad 143 \]
\[ h_{\mathcal{F}}, \quad 185 \]
\[ h_{\mathcal{O}}, \quad 184 \]
\[ \{ \}, \quad 201 \]
\[ j \text{- vector part}, \quad 96 \]
\[ k \text{- blade}, \quad 94 \]
\[ k \text{- vector}, \quad 93, 94 \]
\[ k \text{- volume}, \quad 64, 103 \]
\[ o, \quad 190 \]
adjoint, 144
Aida, 90
angle, 89
between subspaces, 124
between vectors, 59
bivector, 85
antisymmetrized geometric product, 118
associated homogeneous equation, 47
associative, 6
axial vector, 114
basis, 27
\[ \mathcal{G}^3, \quad 82 \]
bivector, 81
direction, 197
blade, 94
canonical basis, 82, 95
car analogy, 14, 17
Cartan-Dieudonnée theorem, 175
cartesian form, 85
Cauchy-Schwarz inequality, 58, 83
Cavalieri’s principle, 65, 103
centralizer, 44
change of basis
matrix, 156
vector, 44
characteristic polynomial, 164
circular reasoning, 185
cm3 notebook, x, 189, 200
cohere, 127, 197
column space, 146
commutative, 5
commutator, 118, 179
complex number, 85
cartesian form, 85
polar form, 85
condition number, 185
conformal model, 190
conformal split, 192
conformal transformation, 193
dilate, 194
invert, 194
reflect, 194
rotate, 193
translate, 193
conjugate, 85
contrapositive, 202
converse, 202
coordinate-based, 9
coordinate-free, vii, 3, 8, 9, 51, 77, 89, 107, 121, 153
coordinates
oriented length, 8
with respect to a basis, 28
corollary, 204
correlation, 62
matrix, 172
counterexample, 203
covariance, 195
Cramer’s rule, 159
cross product, 112, 150
cyclic reordering, 97
de Moivre’s theorem, 88
determinant
linear transformation, 151
matrix, 157
diagonal, 39
matrix, 42
diagonalizable, 161
orthogonally, 176
diagonalize, 163
dilation, 194
dimension, 30, 31
direct proof, 203
direct representation, 190
circle, 192
line, 192
plane, 192
sphere, 192
direct sum, 66, 93
distance, 122
distributive, 5
dual, 109
dual representation, 190
circle, 191
line, 191
plane, 191
sphere, 191
duality, 111
eigenblade, 168
eigenspace, 160, 161
eigenvalue, 160
eigenvector, 160
entangled, 90
equivalent, 202
even subalgebra, 97
exponential, 85, 88, 180
extended fundamental identity, 115
exterior algebra, 111

finite dimensional, 32
Fourier expansion
multivector, 113
vector, 63, 69
function, 205
function space, 17
fundamental identity
$G^3$, 82
$G^n$, 115

GAlgebra, viii, xii
Gaussian elimination, 157
geometric algebra
$G^3$, 73
$G^n$, 93
geometric multiplicity, 160
geometric product
$G^3$, 82
$G^n$, 93
precedence, 82
Google, 162
grade, 96, 137
grade involution, 113
Gram-Schmidt orthogonalization, 64, 65, 103, 122, 189
Grassmann algebra, 111
group, 136

homogeneity, 10
homogeneous, 190
homomorphism, 136
hyperplane, 128

identity
matrix, 39

transformation, 151
if and only if, 202
if-then, 202
implies, 202
indirect proof, 203
infinite dimensional, 32
inherit, 20
inner product
$G^n$, 101
$\mathbb{R}^n$, 56
geometric interpretation, 123
indefinite, 189
oriented lengths, 51
standard, 57
inner product space, 57
intersection, 201
intrinsic, 9, 28, 44, 153
invariant subspace, 166
inverse
matrix, 39
multivector, 100
inversion, 114, 194
isotropy, 10
join, 198

kernel, 47
Lagrange polynomial, 50
Lagrange’s identity, 83
Laplace expansion, 159
law of cosines, 58
least squares, 68, 70, 184
left contraction, 101
Legendre polynomials, 69
lemma, 204
length, 4
linear transformation, 135
linear combination, 22
linear dependence, 24
linear independence, 24, 108
linear model, 12
linear transformation, 135
square root, 171
linearize, 193
lunar laser ranging, 132

Markov process, 43
matrix, 33
diagonal, 41, 42
matrix inverse, 39
matrix representation, 153, 154
meet, 198
metric space, 69
multivector, 82, 93

norm
\( \mathbb{G}^n \), 99
\( \mathbb{R}^n \), 14
complex number, 86
Frobenius, 164, 185
Hilbert-Schmidt, 164
inner product space, 58
operator, 143, 184
oriented area, 73
oriented length, 3
oriented solid, 79
trace, 164
normal transformation, 147, 165
normalize, 52, 59
normalized, 190
notation, 108
null, 189
null vector, 190
nullspace
  linear transformation, 140
  matrix, 47
NumPy, 70

one-to-one, 205
one-to-one correspondence, 206
onto, 205
orientation, 75, 107
  opposite, 99
  orthonormal basis, 99
  same, opposite, 75, 99
oriented
  area, 73
  length, 3
  solid, 79
oriented arc, 86
origin, 11
orthogonal
  basis, 53
  inner product space, 57
  matrix, 174
  oriented length, 53
to a subspace, 64
transformation, 173
vectors, 53

orthogonal complement, 66, 109
orthonormal basis, 53, 189
outer product
  \( \mathbb{G}^n \), 101
  oriented lengths, 76
outermorphism, 123, 148
parallelepiped, 64
parallelogram identity, 58, 61
parameter, 11
Parseval’s identity, 69
part, 96
particular solution, 47
Pauli algebra, 88
Pauli equation, 88
permutation
  even, odd, 98, 107, 118
permutation parity theorem, 98
phase space, 12
point pair, 198, 199
point-normal equation, 55
polar decomposition
  linear transformation, 183
  matrix, 184
polar form, 85
polarization identity, 58
positive semidefinite, 183
precedence, 82
preserve, 123
principal component analysis, 172
project, 52
  \( \mathbb{G}^n \), 121
  inner product space, 67
  oriented length, 52
proof, 203
  by contradiction, 203
proposition, 202
pseudoscalar, 96, 99
unit, 84
pseudovector, 114
Pythagorean theorem, 58
  areas, 77
quaternion, 87
range, 140
rank
  \( \text{Gr} \)1gebra, 50
  linear transformation, 147
  matrix, 146
reciprocal basis, 119, 158
reflect, 128
\( \mathbb{G}^n \), 128
\( \mathbb{G}^{n+1,1} \), 194
reject
\( \mathbb{G}^n \), 121
inner product space, 67
relativity
inner product space, 67
relativity
general, 132
special, 61, 189
reverse, 97, 98
Rodrigues’ formula, 92
rotate
\( \mathbb{G}^{3} \), 89
\( \mathbb{G}^{n} \), 126
\( \mathbb{G}^{n+1,1} \), 193
rotation
two reflections, 131
row space, 146
scalar, 4
self-adjoint transformation, 169
set, 201
similar matrices, 158
simultaneous diagonalizability, 165
singular value decomposition
linear transformation, 181
matrix, 182
singular values, 181
skew
matrix, 177
transformation, 177
spacetime, 61, 189
span
subspaces, 66
vectors, 22
spectral theorem, 170
spinor, 87, 97
standard basis, 27, 56
standard model, 190
subset, 201
subspace, 20
subtraction, 6
Sylvester’s law of inertia, 189
symbols, ix
symmetric
matrix, 169
transformation, 169
SymPy, viii
system of linear equations, 45
theorem, 203
torque, 114
trace
linear transformation, 164
matrix, 44
transition matrix, 44
translation, 193
transpose, 41
triangle inequality, 59
trivector, 81
uncertainty relations, 44
union, 201
vector, 3, 12, 81
bound, 11
direction, 3, 194
free, 3
normal, 55, 191, 193
tangent, 199
unit, 52
vector operations
\( \mathbb{R}^n \), 13
oriented lengths, 4
vector space, 7, 13, 15
volume, 64, 103
well defined, 75
\( \mathbb{R}^{r,s} \), 189
det(\( A \)), 157, 159
tr(\( f \)), 164
bivector addition, 75
norm, 99
projection, 122
reflection, 129
reverse, 97
rotation, 126